



Seat No.	
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**T.E. (Computer) (Semester – I) Examination, 2014
(2008 Course)
DIGITAL SIGNAL PROCESSING**

Time : 3 Hours

Max. Marks : 100

- Instructions :** 1) Answers to the **two** Sections should be written in **separate** answer books.
2) Answer **any three** questions from **each** Section.
3) **Neat** diagrams must be drawn **wherever** necessary.
4) Figures to the **right** side indicate **full** marks.
5) **Use** of calculator is **allowed**.
6) Assume **suitable** data, if **necessary**.

SECTION – I

1. a) Define a different standard discrete time signals and prove that $\delta(n) = u(n) - u(n-1)$. 8
b) Test the system $y(n) = x(n)u(n)$ for causality, linearity, stability and time invariance. 8
- OR
2. a) Determine whether systems are time invariant or variant : 10
i) $y(n) = x(n) - x(n-1)$
ii) $y(n) = nx(n)$
iii) $y(n) = x(-n)$
iv) $y(n) = x(n) \cos \omega_0 n$
v) $y(n) = |x(n)|$
- b) Prove that the discrete time sinusoidal signal is periodic only if its frequency f_0 is rational 6
3. a) State and prove following properties of FT 12
i) Linearity
ii) Periodicity
iii) Frequency shift.
- b) Compute DFT of the following sequence using linear transformation matrix $x(n) = \{0, 1, 2, 3\}$. 6
- OR
4. a) Find N-point DFT of $x(n) = a^n$ for $0 \leq n \leq N-1$. 6
b) Compare :
i) DFT and DTFT
ii) Circular convolution and linear convolution. 8
c) Find the sequence $x(n)$ if its Fourier transform $X(e^{j\omega}) = 1$. 4



5. a) Explain Radix-2 DIT FFT algorithm. 8
 b) Find the Z-transform and ROC of the sequence :
 $x(n) = (-1/3)^n u(n) - (1/2)^n u(-n-1)$. 8
 OR
6. a) Define inverse z-transform. Explain any one method to calculate inverse z-transform. 8
 b) Calculate DFT of the sequence $x(n) = \cos(\pi n/2)$ where $N = 4$ using DIFFFT algorithm. 8

SECTION – II

7. a) How to determine the causality and stability from $H(z)$? 4
 b) Define system function $H(Z)$. How it is obtained from the general difference equation ? 4
 c) Find and draw magnitude, phase response of system function : 8

$$H(Z) = \frac{z+1}{z(z-1)}$$

OR

8. a) With example, explain the method of simple geometric interpretation (Construction) to obtain the frequency response of DT system. 8
 b) Determine impulse response of $y(n) = 2x(n) - x(n-1) - 3y(n-1) - 2y(n-2)$. 8
9. a) Compare between FIR and IIR filters. State the ideal frequency response characteristics of DT filter. 8
 b) Convert an analog filter with system function $H(s)$ into digital IIR filter using impulse invariance method. 10

$$H(s) = \frac{10}{s^2 + 7s + 10}$$

OR

10. a) Explain the design steps of FIR filter with example using windowing method. 8
 b) Explain impulse invariance method for the design of IIR filters. What are the problems associated with this method ? 10
11. a) Explain the direct form – I and direct form – II of IIR filter structure. 8
 b) Compare DSP processor and general purpose processors. 8
 OR
12. a) Explain different types of standard architecture for microprocessor. 8
 b) Draw and explain in brief the cascade form of FIR filter structure. 8